

RESOURCE-CONSTRAINED ON-DEVICE LEARNING BY DYNAMIC AVERAGING

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Workshop on Parallel, Distributed and Federated Learning - ECML PKDD 2020



ML2R



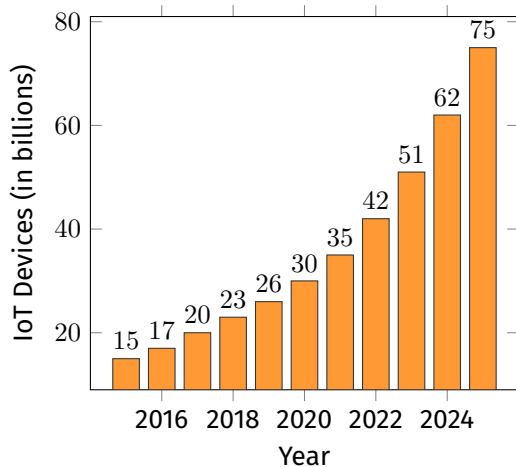
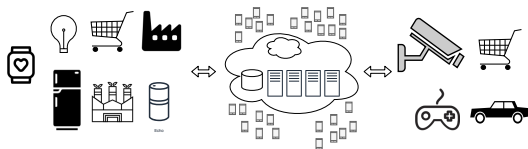
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Motivation

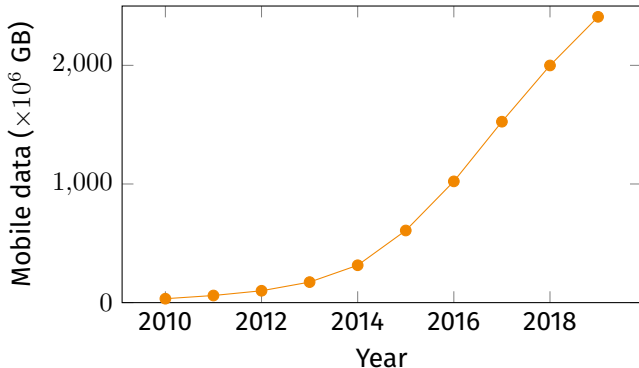
- ▶ Data is generated by IOT devices
- ▶ Data contains valuable information
- ▶ Traditional setting does not scale



[1] Statista - Number of connected IoT Devices

Motivation - Problems with traditional machine learning

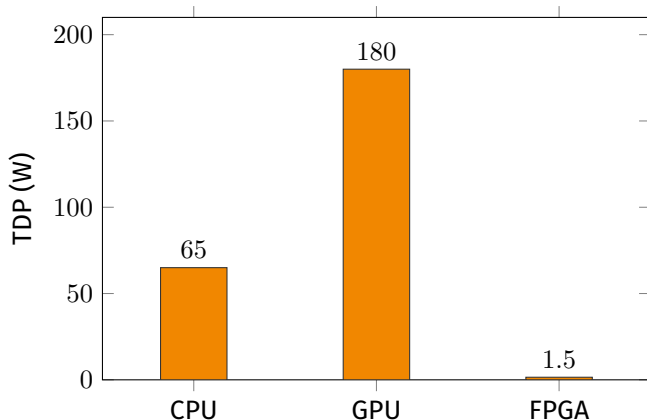
- ▶ Storage
- ▶ Bandwidth
- ▶ Privacy
- ▶ High energy consumption



- [1] Energy consumption of mobile data transfer - Increasing or decreasing?
Evaluating the impact of technology development & user behavior
- [2] <https://findikaattori.fi/en/125>

Motivation - Problems with traditional machine learning

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[1] Intel i7-10700

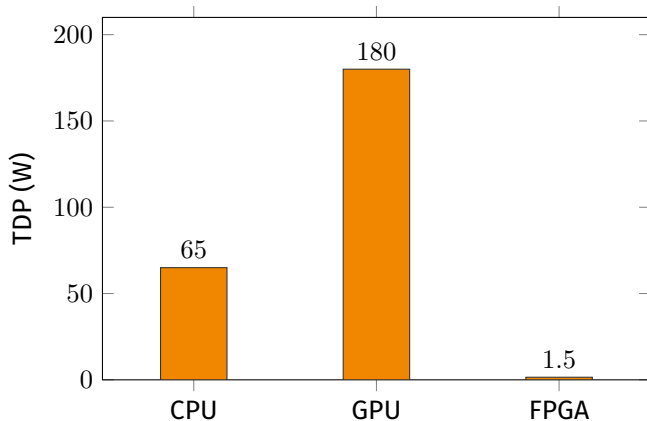
[2] Nvidia GTX 1080

[3] Kintex-7 KC705 - Hardware Accelerated Learning at the Edge, Muecke et. al, 2019

Motivation - Problems with traditional machine learning

- ▶ Storage
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Solution: On-Device Learning



[1] Intel i7-10700

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Motivation - Challenges in Resource-Constrained-Systems

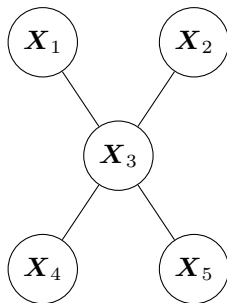
- ▶ Limited processing power / instruction sets
- ▶ Battery powered
- ▶ Network limitations

Goal: Energy- and communication efficient algorithm



Exponential Family Models ¹

- ▶ Model distribution \mathbb{P} of p -dimensional discrete random vector \mathbf{X}
- ▶ Exploit independencies between \mathbf{X}_i 's for compact representation



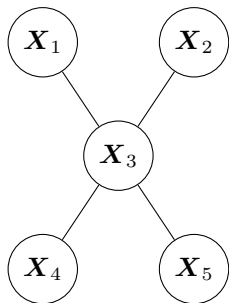
¹Martin Wainwright and Michael Jordan, Graphical Models, Exponential Families, and Variational Inference, 2008

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$$\mathbb{P}_{\boldsymbol{\theta}}(\mathbf{X} = \mathbf{x}) = \frac{\exp(\langle \phi(\mathbf{x}), \boldsymbol{\theta} \rangle)}{Z(\boldsymbol{\theta})}$$

- ▶ $\boldsymbol{\theta} \in \mathbb{R}^d$ is our parameter vector
- ▶ $\phi(\mathbf{x}) : \mathcal{X} \mapsto \{0, 1\}^d$ sufficient statistic
- ▶ $Z(\boldsymbol{\theta})$ is the normalizer

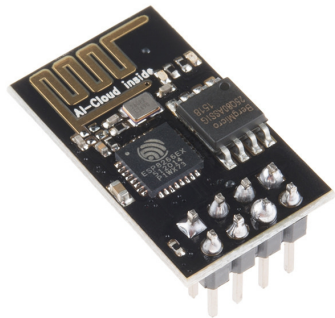


¹Martin Wainwright and Michael Jordan, Graphical Models, Exponential Families, and Variational Inference, 2008

Integer Exponential Family ¹

- ▶ Restrict $\theta \subseteq \{p \mid p \in \mathbb{N} \wedge p \leq k\}^d = \mathbb{N}_{\leq k}^d$
- ▶ Change base from \exp to 2
- ▶ Store probabilities as fraction a/b

$$\mathbb{P}_{\theta}(\mathbf{X} = \mathbf{x}) = \frac{2^{\langle \phi(\mathbf{x}), \theta \rangle}}{Z(\theta)}$$



Esp 8266

¹Nico Piatkowski, Exponential families on resource-constrained systems, 2018

Integer Exponential Family - Learning

- ▶ Given a dataset $\mathcal{D} = \{\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(n)}\}$
- ▶ Estimate $\boldsymbol{\theta}$ using maximum-likelihood-estimation
- ▶ Denote $\hat{\boldsymbol{\mu}} = \frac{1}{n} \sum_{\mathbf{x} \in \mathcal{D}} \phi(\mathbf{x})$ and solve

$$\boldsymbol{\theta}^* = \underset{\boldsymbol{\theta}}{\operatorname{argmin}} \log Z(\boldsymbol{\theta}) - \langle \boldsymbol{\theta}, \hat{\boldsymbol{\mu}} \rangle$$

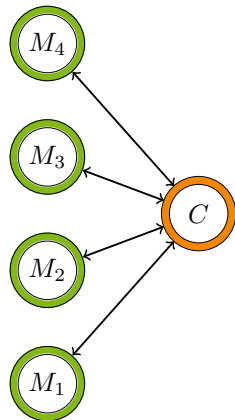
Iterative Learning:

- ▶ Update $\hat{\boldsymbol{\mu}}_t$ as running average
- ▶ Solve problem for $\hat{\boldsymbol{\mu}}_t$

Distributed machine learning

Setting

- ▶ Set of m learners connected to coordinator
- ▶ Data-generating-distribution $Q(\mathcal{X}, \mathcal{Y})$
- ▶ Online round-based learning process



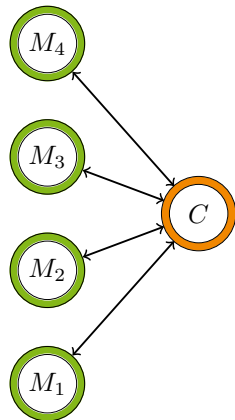
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Questions?

- ▶ What do we communicate?
- ▶ When do we communicate?
- ▶ How to merge information?



What do we communicate?

Protocol	Centralized	Naïve	Privacy
Send	μ_i	$\{\mu_i, \theta_i\}$	θ_i
Receive	θ	$\{\hat{\mu}, \hat{\theta}\}$	$\hat{\theta}$

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- Assuming 16 learners, problem dimension 1000, 32 bit per parameter, 3 bit for integer

(bytes)	Centralized	Naïve	Privacy
Regular	1.152.000	2.304.000	1.536.000
Integer	456.000	912.000	144.000
Reduction	2.5	2.5	10

When do we communicate?

Periodic synchronization

- ▶ Transmit changes on data arrival
- ▶ Control frequency via parameter b
- ▶ Transmit if:

$$t \bmod b = 0$$

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Periodic synchronization

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$$t \bmod b = 0$$

Dynamic synchronization

- ▶ Define reference-vector $\mathbf{r} \in \mathbb{N}^d$
- ▶ Define divergence-threshold $\Delta \in \mathbb{N}$
- ▶ Transmit if:

$$\|\boldsymbol{\theta}^i - \mathbf{r}\|_2^2 \geq \Delta$$

Model aggregation

How to combine the data?

- ▶ Focus on simple average

$$\hat{\theta} = \frac{1}{m} \sum_{i=1}^m \theta^i$$

- ▶ Floored average can be calculated using integer only

$$\bar{\theta} = \left\lfloor \frac{1}{m} \sum_{i=1}^m \theta^i \right\rfloor = \left(\sum_{i=1}^m \theta^i \right) \gg \log_2(m)$$

- ▶ Hierarchical reduction to prevent overflows

$$\left\lfloor \frac{a+b}{2} \right\rfloor = (a \wedge b) + ((a \oplus b) \gg 1)$$

Theoretical guarantees

Bound approximation errors:

- ▶ Integer exponential family models are not arbitrary worse Error = ϵ ¹
- ▶ Error of dynamic avg. is bounded over periodic error²
- ▶ Distance between averages is bounded by dimension: $\|\hat{\theta} - \bar{\theta}\|_2^2 \leq \sqrt{d}$

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Theoretical guarantees

Bound approximation errors:

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 - ▶ Distance between averages is bounded by dimension: $\|\hat{\theta} - \bar{\theta}\|_2^2 \leq \sqrt{d}$
- ▶ Combined error is bounded!

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Experimental Evaluation

Questions

- ▶ Periodic vs. Dynamic averaging?
- ▶ Regular vs. integer exponential family?
- ▶ Different communication schemes?

Criteria

- ▶ Model quality?
- ▶ Bandwidth savings?
- ▶ Energy savings?

Experimental Evaluation - General setup

- ▶ Distributed learning environment with 16 clients
- ▶ Estimation of graph structure on holdout dataset
- ▶ Integer learner parameter space $\mathbb{N}_{\leq 8}$
- ▶ Horizontal partition of data
- ▶ Evaluation of system performance via cumulative 0/1 loss:

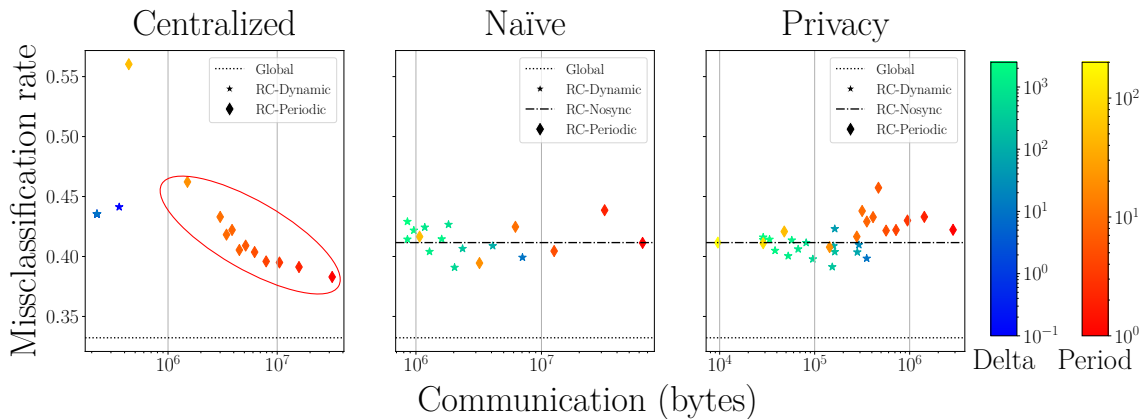
$$\frac{1}{Tm} \sum_{t=1}^T \sum_{i=1}^m \frac{1}{|S_i^t|} \sum_{(\mathbf{x}, y) \in S_i^t} \ell(\mathbf{x}, y | \boldsymbol{\theta}_i^t)$$

Experimental Setup - Procedure and parameters

Online round-based procedure:

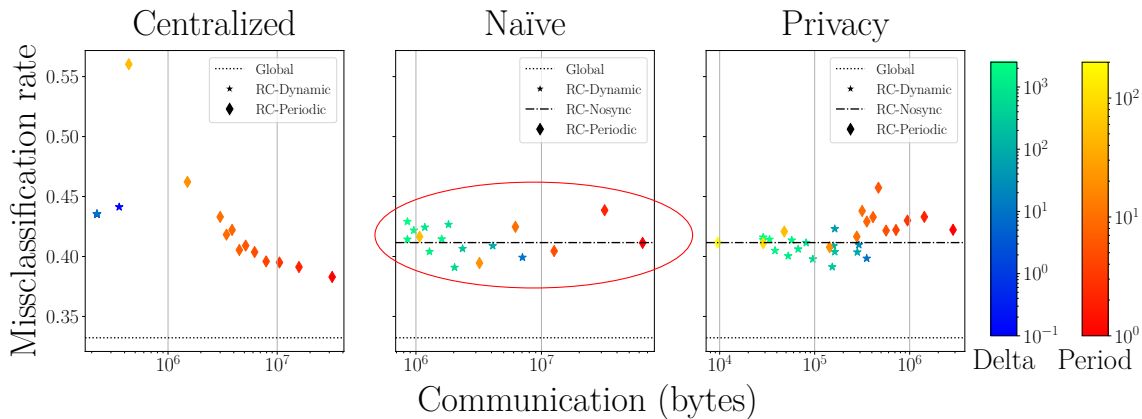
- ▶ Receive a batch of data ($b_s = 10$)
- ▶ Predict labels for batch, compute performance
- ▶ Update $\hat{\mu}$ and run optimization for a given budget ($i = 10$)
- ▶ Communicate depending on protocol

Result - Privacy Preserving Averaging vs. Centralized



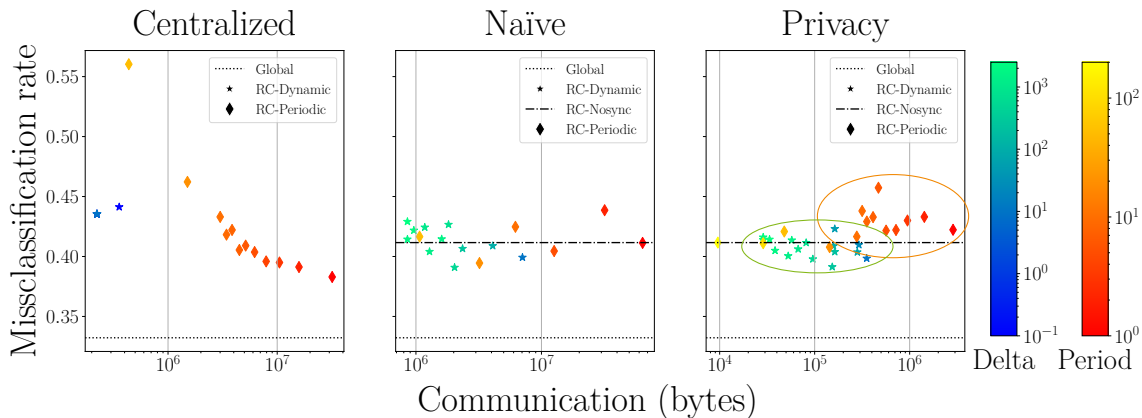
- Privacy-aware averaging retains performance while using less bandwidth

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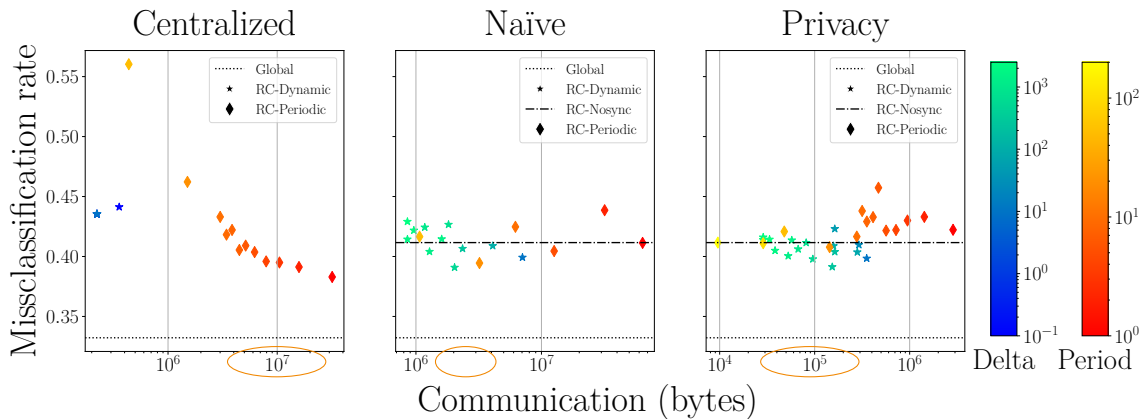
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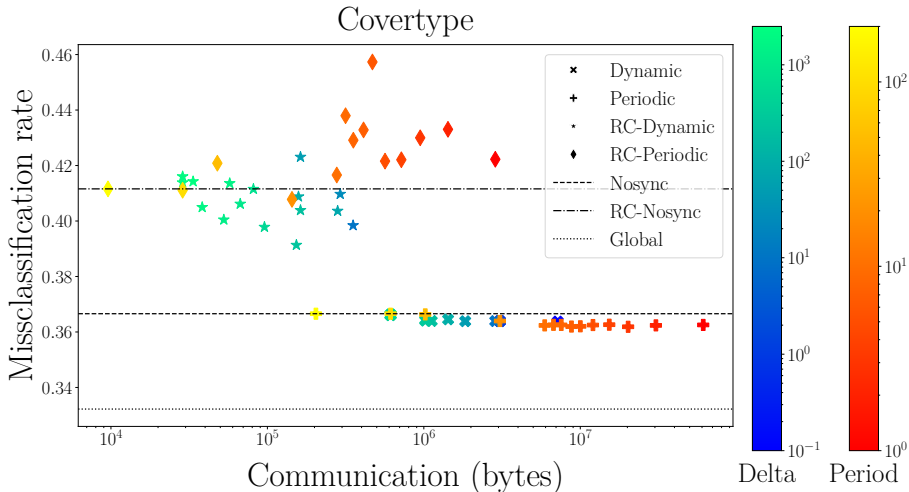
► Privacy-aware averaging retains performance while using less bandwidth

Result - Privacy Preserving Averaging vs. Centralized



- Privacy-aware averaging retains performance while using less bandwidth

Result - Privacy Preserving Averaging - Covertypes



Future work

- ▶ Scale number of learners
- ▶ Communication vs. Rounding impact
- ▶ Methods to select optimal hyperparameters
- ▶ Modular parameter updates
- ▶ Adaptation to non i.i.d / time-variant data

Conclusion

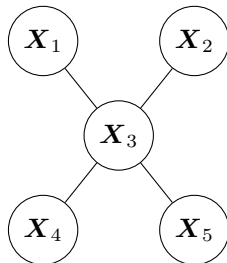
- ▶ Distributed integer-only learning is possible
- ▶ Energy vs. Performance-Tradeoff
- ▶ Bandwidth reduction of $193\times$
- ▶ Estimated energy reduction of $67\times$



Backup

Exponential Family Models - Sufficient statistic

- ▶ Assume binary variables ($\forall i \mathcal{X}_i = \{0, 1\}$)
- ▶ Let $\mathbf{x} = [0, 1, 0, 0, 1]^\top$
- ▶ $\phi(\mathbf{x}) = [\phi_{x_1x_3}(\mathbf{x}), \phi_{x_2x_3}(\mathbf{x}), \phi_{x_3x_4}(\mathbf{x}), \phi_{x_3x_5}(\mathbf{x})]^\top$



$$\phi_{x_1x_3}(\mathbf{x}) = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \quad \phi_{x_2x_3}(\mathbf{x}) = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \quad \phi_{x_3x_4}(\mathbf{x}) = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \quad \phi_{x_3x_5}(\mathbf{x}) = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

- ▶ $d = \sum_{(s,t) \in E} \mathcal{X}_s \cdot \mathcal{X}_t = 4 \cdot 2^2$
- ▶ Assuming 10 states per variable, we store $4 \cdot 10^2$ instead of 10^5